

IN THE CLAIMS:

Please amend claims 1- 13 as follows:

1. (Currently Amended) ~~Iterative~~An iterative method for decoding a signal vector Y obtained from N sampled signals in a space-time communication system with M ~~transmit~~transmission antennae and N ~~receiver~~receiving antennae, with N greater than or equal to M , with a view to obtaining an estimation of the symbols of the signals transmitted; characterized in that each iteration comprises the following steps:

- Pre-processing of the vector Y in order to maximize the signal to noise+interference ratio in order to obtain a signal \tilde{r}^{ℓ} ,

- Subtraction from the signal \tilde{r}^{ℓ} of a signal \hat{z}^{ℓ} by means of a subtractor, the signal \hat{z}^{ℓ} being obtained by reconstruction post-processing of the interference between symbols from the symbols estimated during the preceding iteration,

- Detection of the signal generated by the subtractor in order to obtain, for the iteration in progress, an estimation of the symbols of the signals transmitted;

and in that, the N signals being processed by time intervals T corresponding to the time length of the linear space-time code associated with the transmitted signals, the pre-processing step involves the matrix B in order to maximize the signal to noise+interference ratio, the transfer function of which is:

$$B^\ell = \text{Diag} \left(\frac{1}{\rho_{t-1}^2 A_i^\ell + \frac{N_0}{E_s}} \right)_{1 \leq i \leq MT} \cdot C^H V^\ell$$

$$\text{with } V^\ell = \left[\frac{1 - \rho_{t-1}^2}{\frac{N_0}{E_s}} \cdot C \cdot C^H + Id_N \right]^{-1} ; \quad A^\ell = \text{diag} (C^H \cdot V^\ell \cdot C) ;$$

wherein ℓ : iteration index; ρ : standardized correlation coefficient between the real symbols and the estimated symbols; N_0 : noise variance; E_s : mean energy of a symbol; C : extended channel matrix;

and in that the post-processing step involves a matrix D for the reconstruction of the interference between symbols, the transfer function of which is:

$$D^\ell = B^\ell \cdot C \cdot \rho_{t-1} - \text{Diag} \left[\frac{1}{\rho_{t-1}^2 A_i^\ell + \frac{N_0}{E_s}} \right]_{1 \leq i \leq MT}$$

2. (Currently Amended) ~~Method~~ The method according to claim 1, ~~characterized in that~~ wherein the pre-processing step is carried out by operating a matrix multiplication between the signal vector Y and a matrix B , the matrix B being updated at each iteration.

3. (Currently Amended) ~~Method~~ The method according to claim 1 or 2, ~~characterized in that~~ wherein the post-processing step is carried out by operating a matrix

multiplication between the vector of the symbols estimated during the preceding iteration and the matrix D, the matrix D being updated at each iteration.

4. (Currently Amended) ~~Method~~ The method according to claim 2 or 3, ~~characterized in that, wherein~~ for each iteration, the standardized correlation coefficient ρ is calculated, the updating of a matrix being achieved by determining new coefficients of the matrix as a function of the correlation coefficient obtained for the preceding iteration.

5. (Currently Amended) ~~Method~~ The method according to ~~any one of the preceding claims, characterized in that~~ claim 1, wherein in order to determine the correlation coefficient ρ^ℓ for each iteration:

- the signal to interference ratio SINR is calculated using the following

formula:
$$SINR^\ell = \left[\frac{1}{\xi^\ell e^{\xi^\ell} E_1(\xi^\ell)} - 1 \right] \frac{1}{1 - \rho_{\ell-1}^2}$$

and defining the integral exponential $E_1(s) = \int_s^{+\infty} \frac{e^{-t}}{t} dt$

with $\xi^\ell = \frac{\varsigma}{1 - \rho_{\ell-1}^2}$ and $\varsigma = \frac{N_o}{NE_s}$

- the symbol error probability Pr is calculated from the signal to interference ratio $SINR^\ell$; and

- the correlation coefficient ρ^ℓ is then calculated from the symbol error probability Pr.

6. (Currently Amended) ~~Method~~The method according to claim 5, characterized in that wherein it is assumed that $\rho^0 = 0$.

7. (Currently Amended) ~~Method~~The method according to claim 5 or 6, characterized in that, wherein in order to calculate the symbol error probability Pr it is assumed that the total noise is Gaussian.

8. (Currently Amended) ~~Method~~The method according to claim 7, characterized in that wherein the formula corresponding to the constellation originating from a linear modulation transmission is used.

9. (Currently Amended) ~~Method~~The method according to ~~any one of~~ claims 5 to 8, characterized in that, claim 5, wherein in order to calculate the correlation coefficient ρ^ℓ from the symbol error probability Pr, it is assumed that when there is an error, the threshold detector detects one of the closest ~~neighbours~~neighbors to the symbol transmitted.

10. (Currently Amended) ~~Method~~The method according to ~~any one of~~ the preceding claims, characterized in that, claim 1, wherein at the final iteration, the signal leaving the subtractor is introduced into a soft-input decoder.

11. (Currently Amended) ~~Method~~The method according to ~~any one of~~
~~the preceding claims, characterized in that~~claim 1, wherein the information symbols are
elements of a constellation originating from a quadrature amplitude modulation.

12. (Currently Amended) ~~Space-time~~A space-time decoder
implementing a method according to ~~any one of the preceding claims,~~claim 1 for decoding a
signal vector Y obtained from N sampled signals in a space-time communication system with
M ~~transmit~~transmission antennae and N ~~receiver~~receiving antennae, with N greater than or
equal to

M, with a view to obtaining an estimation of the symbols of the signals
transmitted, characterized in that it comprises:

- a pre-processing module of the vector Y for maximizing the signal to
noise+interference ratio in order to obtain a signal \tilde{r}^{ℓ} ,
- a subtractor for subtracting a signal \hat{z}^{ℓ} from the signal \tilde{r}^{ℓ} ,
- a post-processing module for the reconstruction of the interference between
symbols from the symbols estimated during the preceding iteration in order to generate the
signal \hat{z}^{ℓ} ,
- a threshold detector for detecting the signal generated by the subtractor in
order to obtain, for the iteration in progress, an estimation of the symbols of the signals
transmitted;

and in that the N signals being processed by intervals of time T corresponding

to the time length of the linear space-time code associated with the transmission signals, the pre-processing module consists of a matrix B for maximizing the signal to noise+interference ratio, the transfer function of which is:

$$B^\ell = \text{Diag} \left(\frac{1}{\rho_{\ell-1}^2 A_t^\ell + \frac{N_0}{E_s}} \right)_{1 \leq i \leq MT} \cdot C^H V^\ell$$

with $V^\ell = \left[\frac{1 - \rho_{\ell-1}^2}{\frac{N_0}{E_s}} \cdot C \cdot C^H + Id_N \right]^{-1}$; $A^\ell = \text{diag} (C^H \cdot V^\ell \cdot C)$;

wherein ℓ : iteration index; ρ : standardized correlation coefficient between the real symbols and the estimated symbols; N_0 : noise variance; E_s : mean energy of a symbol; C: extended channel matrix;

and in that the post-processing module consists of a matrix D for the reconstruction of the interference between symbols, the transfer function of which is:

$$D^\ell = B^\ell \cdot C \cdot \rho_{\ell-1} - \text{Diag} \left(\frac{1}{\rho_{\ell-1}^2 A_t^\ell + \frac{N_0}{E_s}} \right)_{1 \leq i \leq MT}$$

13. (Currently Amended) ~~Decoder~~The decoder according to claim 12,
~~characterized in that~~wherein it comprises a soft input decoder receiving the signal originating
from the subtractor during the final iteration.